



HEIDENHAIN

## Encoders for Elevators

**HEIDENHAIN Corporate Group solutions for your requirements**

**HEIDENHAIN | AMO | RENCO**



# Solutions with additional benefits for today's elevator requirements

Our encoders ensure full-elevator safety and comfort by monitoring the main motor, door motor and shaft copying system. The HEIDENHAIN, AMO and RENCO brands are specialists for your elevator applications, serving conventional and upcoming elevator technologies.

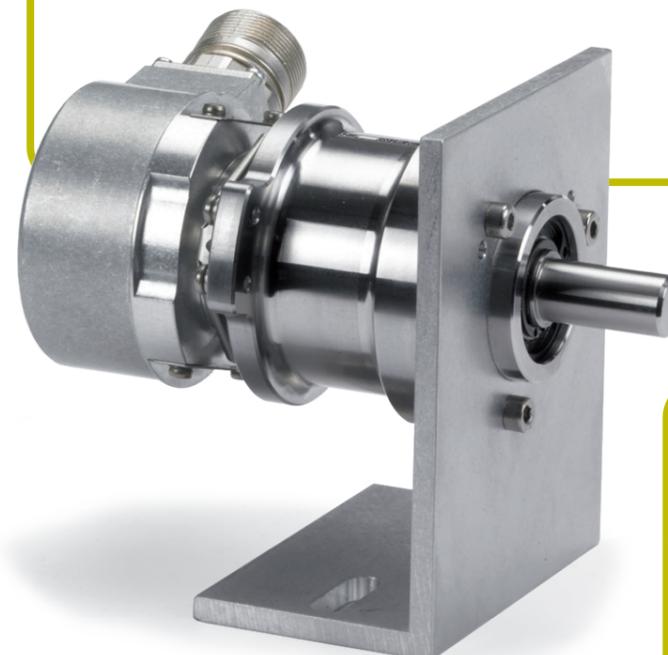
## Main motor

- High signal quality
- Online self-diagnosis
- High reliability



## Shaft copying and speed monitoring

- Absolute position measurement
- Large permissible axial and radial loads
- High signal quality



## Door motor

- Compact form factor
- Electronic adjustment
- Easy integration





## Next-generation elevator technology

The demands on elevator complexity and travel height are growing. Today's elevators have become high-tech passenger transport systems, a far cry from the simple hoists of previous generations.

Safety and comfort are non-negotiable requirements in modern elevators. Vital to meeting these requirements are elevator encoders from HEIDENHAIN, AMO and RENCO. Installed on the main motor, door motor and shaft copying system, our encoders work tirelessly to ensure smooth travel, correct arrival and efficient door operation. Beyond their extreme reliability in these applications, our encoders can also monitor other elevator functions.

The biggest factor in an elevator's speed, comfort and overall performance is its motor control system. More advanced elevator motors, such as gearless designs, require carefully selected encoders and other motion control components. Rotary encoders are also essential in elevator door motors and digital shaft copying systems. With an extensive range of products, HEIDENHAIN, AMO and RENCO offer the optimal solutions for your elevator control needs.



**Main motor**  
– Condition monitoring  
– Brake monitoring

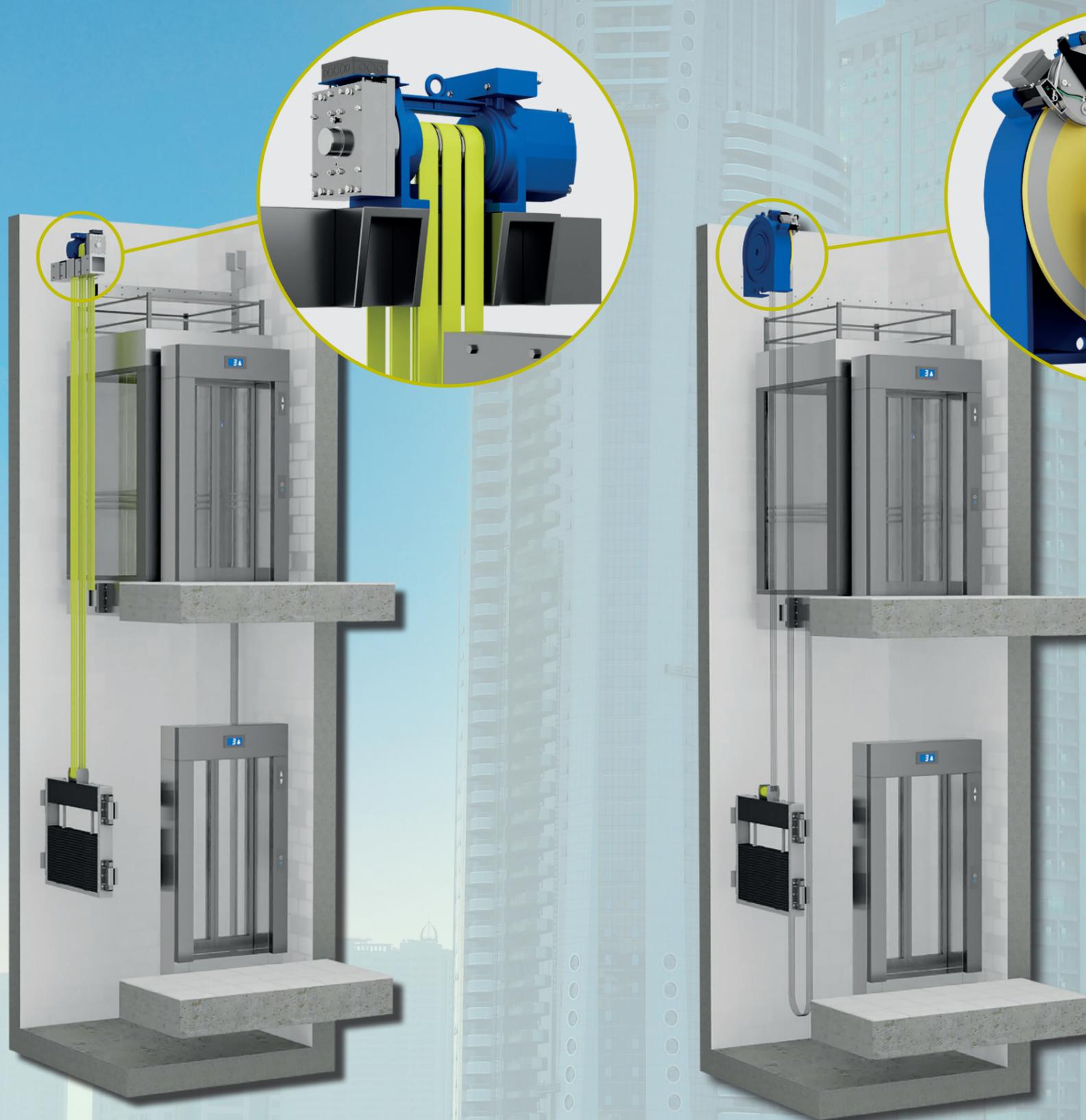
**Shaft copying and speed monitoring**

**Door motor**

### Key requirements for today's elevators:

- Optimal ride comfort
- Accurate car arrival
- Smooth starting and stopping
- Impeccable reliability
- Speed control
- Compatibility with different travel heights

# High-performance motor feedback



## Robust, reliable and high-resolution

These qualities make HEIDENHAIN and AMO rotary encoders trusted solutions for main motor feedback on conventional traction elevators.

High-resolution rotary encoders are the go-to choice for position feedback on main elevator motors. Rotary encoders from HEIDENHAIN and AMO deliver excellent signal quality and high accuracy for exact positioning and high-quality speed control. A rich selection of form factors, mounting types and scanning technologies make them suitable for a variety of motor types, including disc motors, internal rotor motors and external rotor motors.

## Rotary encoder requirements for optimal motion control:

- High positioning accuracy
- Rigid connection to the shaft
- High natural frequency or wide runout tolerances for the coupling
- Easy installation
- Rugged design
- High-performance data interfaces

# Rotary encoders for your elevator motor: Analog or serial, with added monitoring data



## KCI 419Dplus: position feedback and brake monitoring

The KCI 419Dplus inductive rotary encoder does more than provide position feedback on traction elevator motors. It also tracks the brake temperature and detects the brake stroke, all without the help of microswitches, making it an alternative for brake monitoring. The encoder's robust EnDat interface relays the extra brake data to downstream electronics, where the brake status (released or engaged) and the level of brake wear can be determined.

### Your operation and maintenance benefits:

The KCI 419Dplus provides elevator operators with greater system availability and reliability, as well as significantly less maintenance, cabling and installation work.

### ERN 400/1300, ECN 400/1300

#### Rotary encoders with analog output signals

**Area of application**

- Main-motor control

**Characteristics**

- Absolute 1 V<sub>PP</sub> interface or analog 1 V<sub>PP</sub> output signals
- High signal quality
- Stator coupling for easy axial mounting or for compensation of axial error

**Specifications**

- Measuring steps per rev. 23 bits after interpolation
- Operating temperature -40 °C to +100 °C
- Interface 1 V<sub>PP</sub>, EnDat01

### AEF 1300

#### Rotary encoder with purely serial output signals

**Area of application**

- Main-motor control

**Characteristics**

- Absolute interface with purely serial output signals
- Superb EMC robustness thanks to purely serial data transmission
- External and internal temperature measurement
- Stator coupling for easy axial mounting or for compensation of axial error

**Specifications**

- Position values per rev. 23 bits
- Operating temperature -40 °C to +100 °C
- Interface EnDat22

### KCI 419Dplus

#### Rotary encoder with purely serial output signals and brake monitoring

**Area of application**

- Main-motor control

**Characteristics**

- Absolute interface with purely serial output signals
- Brake release monitoring
- Brake wear monitoring
- Temperature monitoring
- Online self-diagnosis
- Digital data transmission

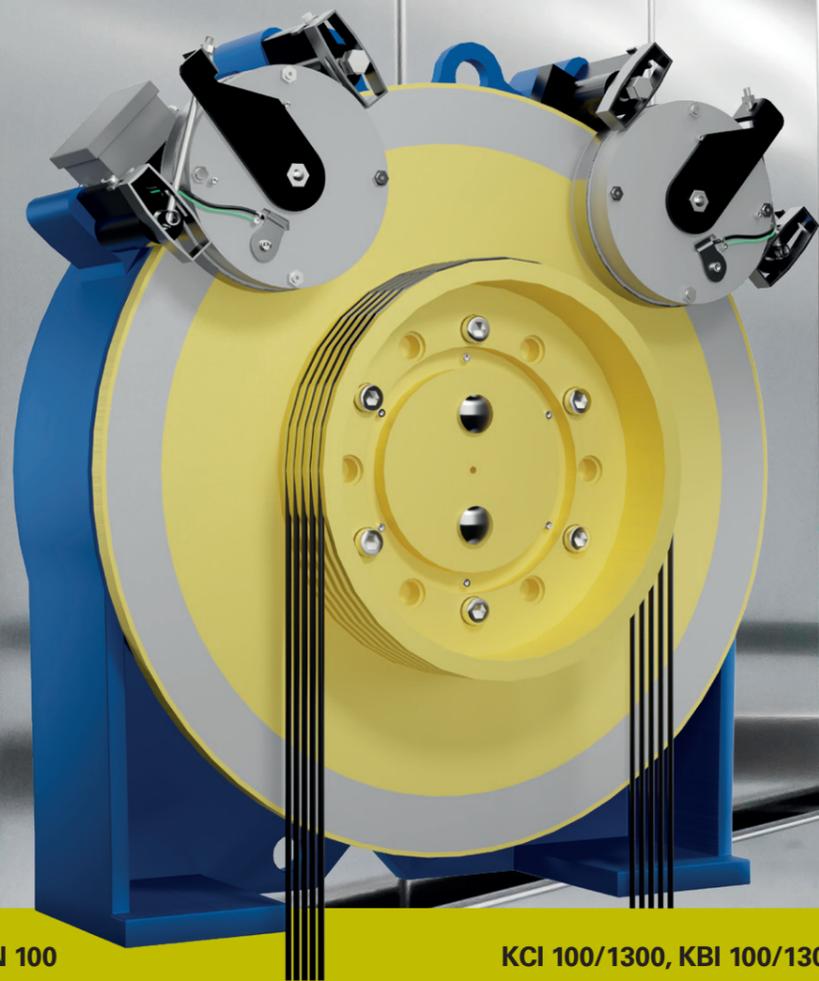
**Specifications**

- Position values per rev. 19 bits
- Measured axial brake stroke 0.5 mm to 1.6 mm
- Operating temperature -40 °C to +100 °C
- Interface EnDat22

#### Extra functionality: operating data for downstream electronics

- Position feedback
- Functional safety
- Online diagnostics
- Sensor information
- Electronic ID label
- Datum shift
- Production data

**EnDat**



### ERN 100, ECN 100

#### Absolute rotary encoders for large shafts

- Area of application**
- Main-motor control

- Characteristics**
- Absolute interface with purely serial output signals or absolute 1 V<sub>PP</sub> interface or analog 1 V<sub>PP</sub> output signals
  - High signal quality
  - Hollow shaft sizes: 25 mm and 50 mm
  - Stator coupling

- Specifications**
- Measuring steps per rev. Up to 23 bits after interpolation
  - Operating temperature -40 °C to +100 °C
  - Interface 1 V<sub>PP</sub>, EnDat01, EnDat22

### KCI 100/1300, KBI 100/1300

#### Absolute inductive rotary encoders for large shafts

- Area of application**
- Main-motor control

- Characteristics**
- Absolute interface with purely serial output signals
  - Compact modular design for easy integration
  - Hollow shaft sizes: 25 mm, 30 mm and 40 mm
  - Immune to magnetic fields and contamination

- Specifications**
- Position values per rev. Up to 20 bits
  - Axial motion of motor shaft  $\leq \pm 0.5$  mm
  - Operating temperature -40 °C to +115 °C
  - Interface EnDat22

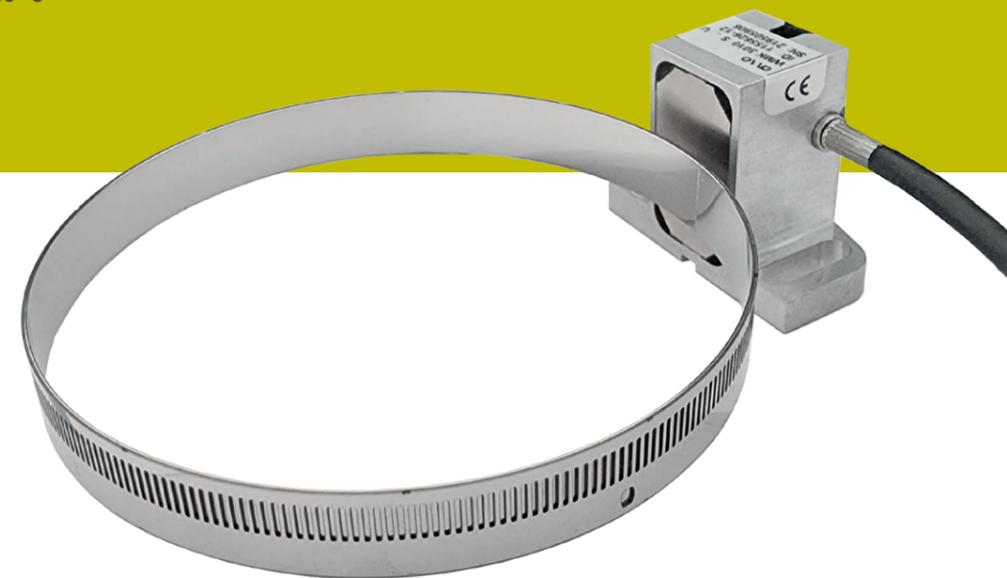
### WMK 3010S/WMR 3010A

#### Incremental inductive rotary encoders with additional operating data

- Area of application**
- Main motors installed in the elevator shaft

- Characteristics**
- Integrated operating data collection
  - Measuring-ring diameter range: 60 mm to 163 mm
  - Compact form factor
  - Immunity to magnetic fields and contamination

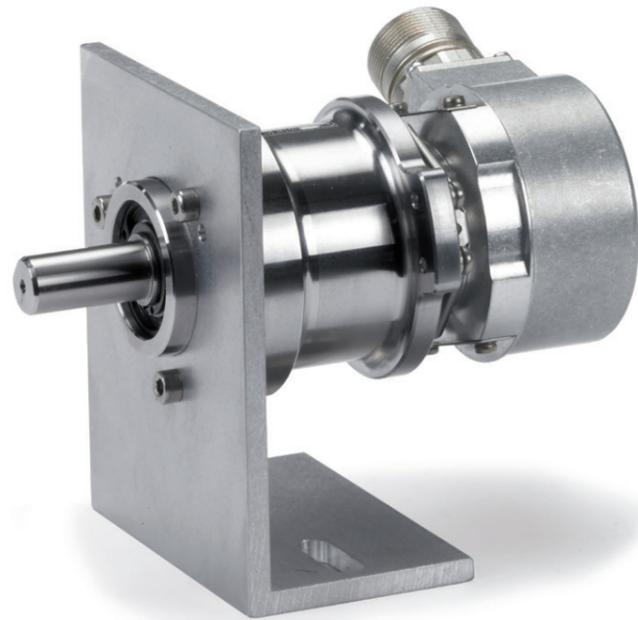
- Specifications**
- System accuracy  $\pm 25$   $\mu$ m
  - Operating temperature -10 °C to +110 °C
  - Interface 1 V<sub>PP</sub>



# Shaft copying and speed monitoring

Measuring an elevator car's exact position in the shaft, and relaying this data to the controller, is essential for guaranteeing smooth braking and accurate car positioning. This is the job of shaft copying systems, which benefit greatly from HEIDENHAIN absolute rotary encoders. Here's why:

- The car's absolute position isn't lost after a power outage
- Always knowing the car's absolute position enables steady control right up to its arrival point



## ExN 400

### Rotary encoder unit for high bearing loads

**Area of application**

- Shaft copying

**Characteristics**

- Absolute multiturn rotary encoder for position feedback
- High signal quality
- Bearing unit for high axial and radial loads

**Specifications**

- Measuring steps per rev. Up to 25 bits
- Revolutions 4096
- Operating temperature -40 °C to +100 °C
- Interface EnDat01, EnDat22
- Bearing load Axial 150 N, radial 350 N



# Rotary encoders for door motors

Elevators don't wait as long at their destinations, and can therefore carry more people throughout the day, if their doors open and close with maximum speed and accuracy. This requires accurate and dynamic position measurement on the door motor. HEIDENHAIN rotary encoders for door motors deliver the position feedback and compact form factor needed in these applications. All of these models have an outside diameter of less than 40 mm.

## ECI 1118

### Absolute inductive rotary encoder

**Area of application**

- Door motors

**Characteristics**

- Absolute interface with purely serial output signals
- Easy-to-integrate design
- Compact form factor
- Immunity to magnetic fields and contamination

**Specifications**

- Position values per rev. 18 bits
- Axial motion of motor shaft  $\leq \pm 0.4$  mm
- Operating temperature -20 °C to +115 °C
- Interface EnDat22



## R35iL

### Incremental rotary encoder for block commutation

**Area of application**

- Door motors

**Characteristics**

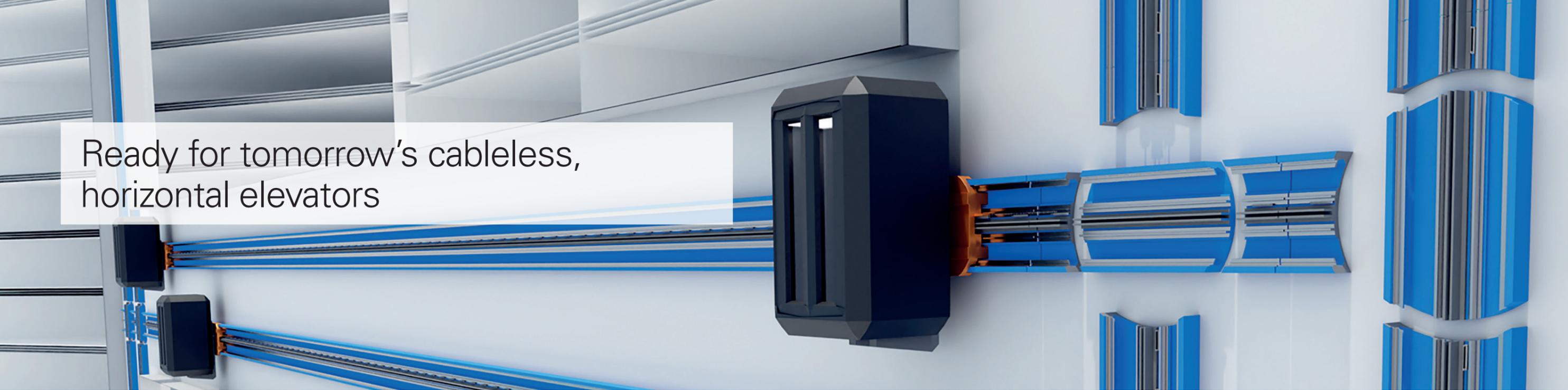
- Feedback system for stepper and BLDC motors
- High signal quality thanks to OPTO-ASIC technology
- Electronic commutation adjustment
- Compact design (height: 8.6 mm)

**Specifications**

- Signal periods per rev. Up to 10000
- Commutation U, V and W signal tracks for up to 32 motor pole pairs
- Operating temperature -30 °C to +115 °C

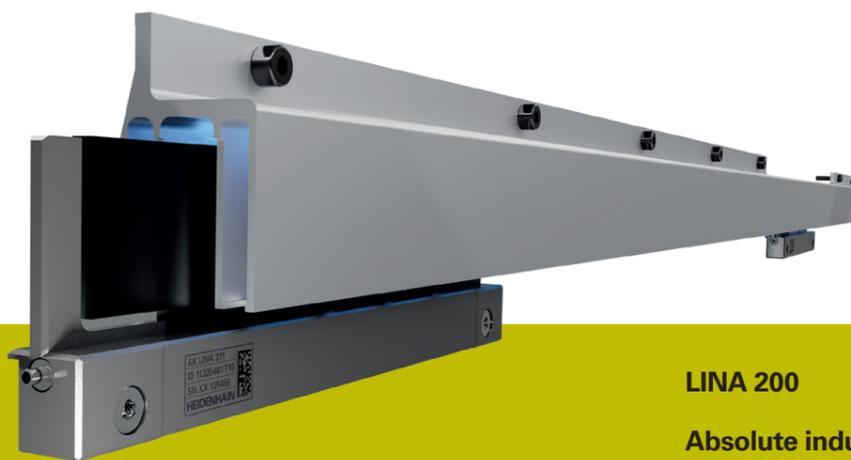


Ready for tomorrow's cableless, horizontal elevators



**HEIDENHAIN: LINA 200**  
Absolute inductive linear encoder for cableless elevators

Freed from the constraints of a cable, future elevators will be able to travel both vertically and horizontally. HEIDENHAIN has already developed an absolute inductive linear encoder for these applications: the LINA 200. The absolute position is calculated based on different signal periods arising from two scale tracks within the encoder's graduation carrier.

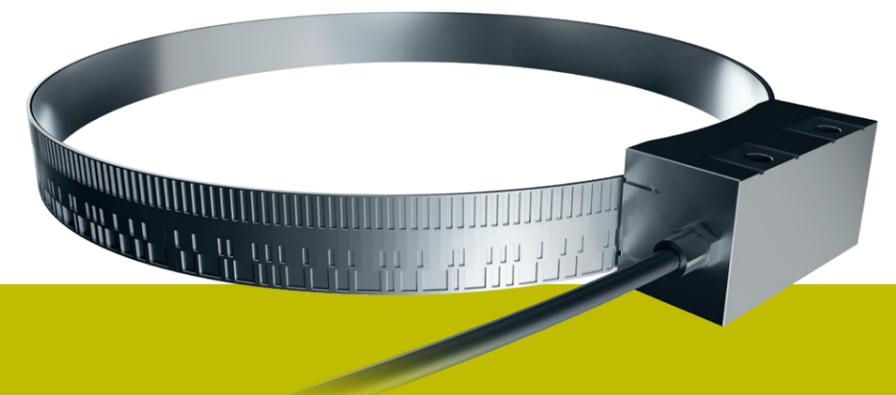


**LINA 200**  
Absolute inductive linear encoder

- Area of application**
- Main-motor control (linear actuator)
- Characteristics**
- Absolute encoder for linear motor control
  - High signal quality for superb passenger comfort
  - Wide runout tolerances thanks to bearingless design
- Specifications**
- Resolution: 18 bits after interpolation
  - Operating temperature: +5 °C to +45 °C
  - Interface: EnDat22

**AMO: WMKA**  
Switch between vertical and horizontal travel

Future cableless elevators will switch between vertical and horizontal travel at in-shaft swivel joints driven by high-power torque motors. These motors can be controlled using the position feedback provided by WMKA modular angle encoders from AMO or exposed linear encoders such as the LIC series from HEIDENHAIN.



**WMKA**  
Absolute modular angle encoder

- Area of application**
- Swivel joints in cableless elevators
- Characteristics**
- Measuring-ring diameter range: 82 mm to 650 mm
  - Compact form factor
  - Universal scanning head design
- Specifications**
- Resolution: 18 bits to 25 bits
  - Operating temperature: -10 °C to +85 °C
  - Interface: EnDat22

## HEIDENHAIN

HEIDENHAIN specializes in high-accuracy measurement and control technology

## RENCO

RENCO is known for its flat-profile, easy-to-mount rotary encoders

## AMO

AMO develops highly robust inductive encoders for linear and rotary applications

Discover more about our solutions

- [elevator.heidenhain.com](http://elevator.heidenhain.com)
- [heidenhain.com/rotary-encoders](http://heidenhain.com/rotary-encoders)
- [structural-monitoring.heidenhain.com](http://structural-monitoring.heidenhain.com)

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